An idea on Bigraphs

28 April 2010.

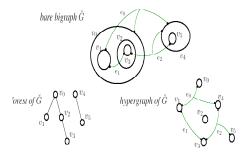
Motivation

To model ubiquitous systems Some concepts:

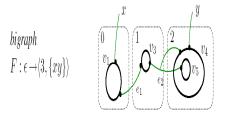
- Space
- Motion
- Interaction

Bare Bigraphs

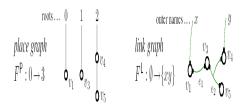
Two independent structures on the same nodes.



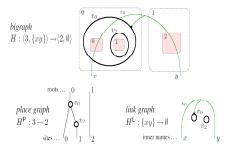
Bigraphs can be composed Each bigraph has an inner face and an outer face.



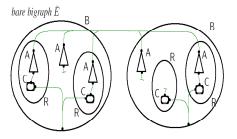
A Bigraph is composed of a link graph and a place graph



A Bigraph is composed of a link graph and a place graph

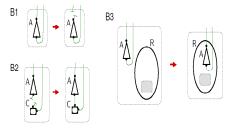


A more realistic example:



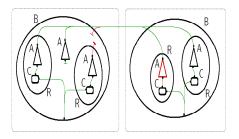
Dynamics of Bigraphs

Some possible reaction rules:

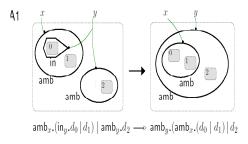


Dynamics of Bigraphs

After applying Rules B_1 , B_3 and B_2 :



Modelling Ambients in Bigraphs



Modelling CCS in Bigraphs

